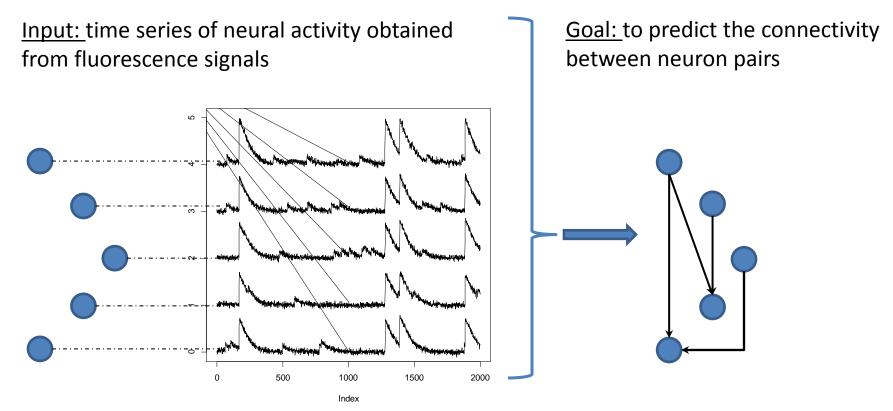
### <u>Supervised Neural Network Structure Recovery</u>

Ildefons Magrans de Abril



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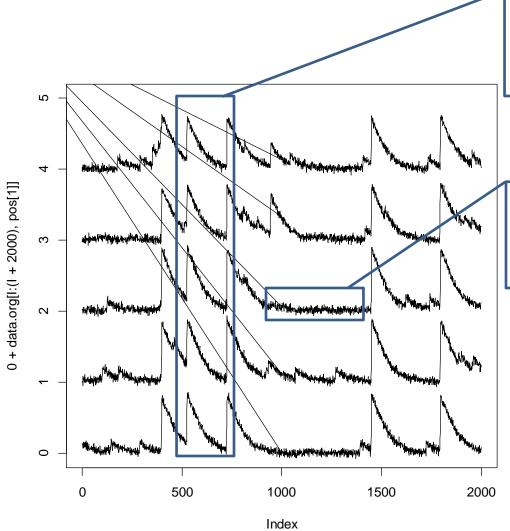
# Challenge setup



#### Dataset consists of:

- Several networks with 1000 neurons
- For each neuron, 1 hour time series of neural activity sampled at 20ms with values normalized in [0,1]
- Training networks contain connectivity labels

# What is hard about this challenge?



### **Episodes of synchronous bursting:**

Time periods conveying low connectivity information

# Background noise and light scattering artifacts:

Noise and signal can be confused

# Slow frame rate of ~20 ms is 10 times slower than neuron's firing dynamic:

 Direct vs indirect effects and causal relationships are hard to detect

## Solution guidelines

#### Idea:

"Optimizing a single connectivity indicator may be a limiting strategy because it will tend work optimally for particular conditions of synchronous bursting and noise."

### **How:**

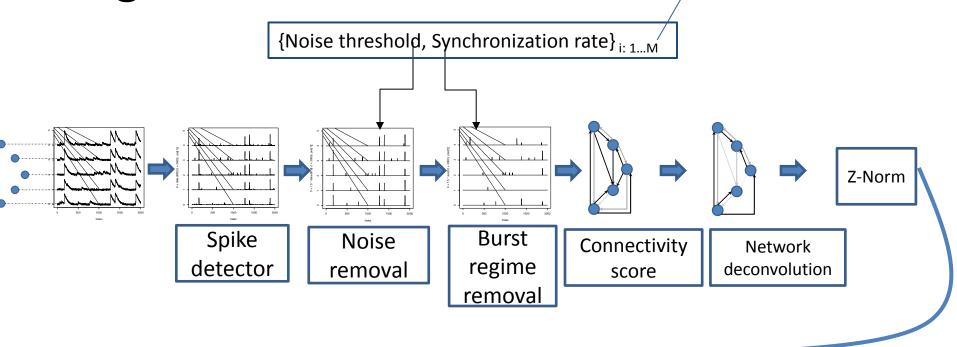
To approximate a function able to combine several connectivity indicators optimized for different conditions of synchronous bursting and noise.

#### **Additional non-functional requirements:**

- Given the large number of connectivity indicators that need to be computed (training and test networks, and for each neuron pair), the computational complexity of connectivity indicators must be low.
- Given the a priori large number of possible solutions to each of the main challenge problems (synchronous bursting, noise and direct vs indirect effects), we favored a modular approach.

### Design overview

We run this feature engineering pipe M times

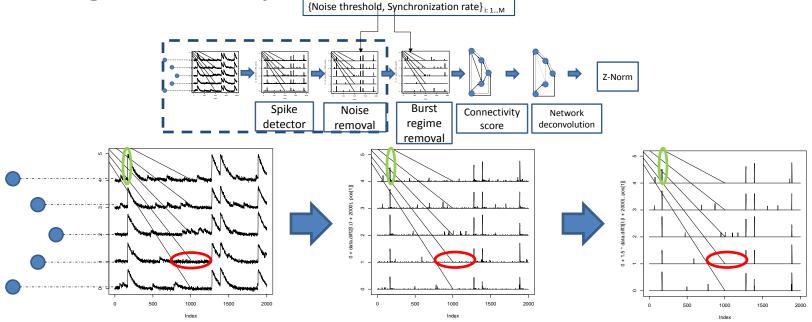


Neuron pair	{NT,SR} <sub>1</sub>	{NT,SR} <sub>2</sub>	{NT,SR}₃	{NT,SR} <sub>M</sub>	True label
1 -> 1	0	0	0	0	0
1 -> 2	0.9	0.87	0.85	0.92	1
2 -> 1	0.9	0.87	0.85	0.92	1
1 -> 3 	0.3	0.34	0.35	0.24	0
N -> N	0	0	0	0	0



F(NN time series, i, j)  $\epsilon$  [0,1]

Building blocks, spike detector and noise removal



**Goal:** To infer the actual spike train of neuron i, given the time series of neural activity:

$$F_i = \{F_i^1, F_i^2, ..., F_i^T\} \rightarrow n = \{n_i^1, n_i^2, ..., n_i^T\}$$

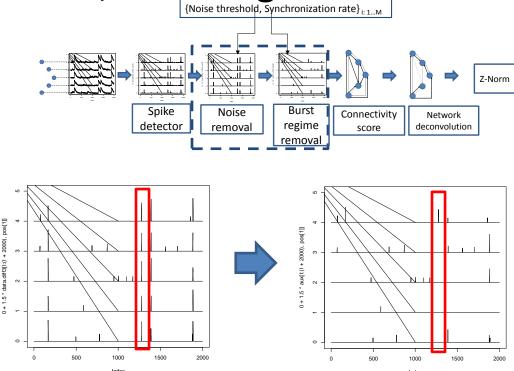
**How:** Fast-oopsi developed by Joshua Vogelstein:

$$\hat{n} = arg \, max_n Pr(n|F)$$

<u>Post-processing:</u> The *Noise Removal* Step removes spikes below a parameter value *Noise Level* <u>Evaluation vs Backward difference</u> (  $n_i^t = F_i^t - F_i^{t-1}$  ): using the complete feature engineering pipeline, the training network *Normal*<sub>1</sub> and a large set of Noise Levels { $NL_1,...,NL_M$ }:

Fast-oopsi	Difference	
mean {AUC <sub>1M</sub> }=0.909	mean {AUC <sub>1M</sub> }=0.902	
max{AUC <sub>1M</sub> }=0.932	max{AUC <sub>1M</sub> }=0.929	

Building blocks, Burst regime removal



**Goal:** To remove episodes of synchronous bursting because they convey low connectivity information

**How:** To remove time steps t in all neurons s.t.

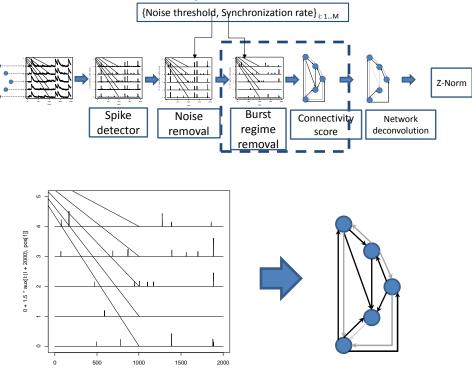
$$\sum_{i=1}^{N} \mathbb{1}\{n_i^t \neq 0\} > SR.N$$

n<sub>i</sub>t: probability of neuron i spiking at time t

N: number of neurons

SR: Synchronization Rate or percentage of neurons allowed to fire at the same time t

### Building blocks, Connectivity score



**Goal:** To compute a connectivity indicator between all neuron pairs given the spike trains computed in previous steps

**Non-functional requirements:** Computational performance should be low

2 training networks + test and validation networks

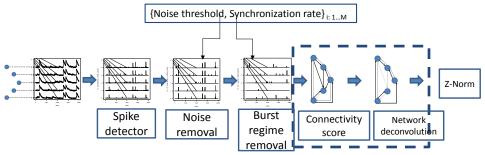
1000 neurons per network

M connectivity indicators for each neuron pair

**How:** Correlation shows good AUC with reasonable computational performance

<u>Limitations:</u> Unable to identify directed connections

### Building blocks, Network deconvolution



**Goal:** To eliminate the combined effect of indirect paths of arbitrary length (Slow frame rate of 20 ms ~ 10 times slower than neuron's firing dynamic)

**How:** Network Deconvolution algorithm developed by Soheil Feizi et Al. 2013:

$$C_{dir} = C_{obs}(I + C_{obs})^{-1}$$

- 1) To normalize in the interval [-1,1] the connectivity score matrix
- 2) To decompose with SVD the matrix obtained in step 1
- 3) To compute the eigenvalues of the deconvolved matrix according to:

$$\lambda_i^d = \frac{\lambda_i}{\lambda_i + 1}$$

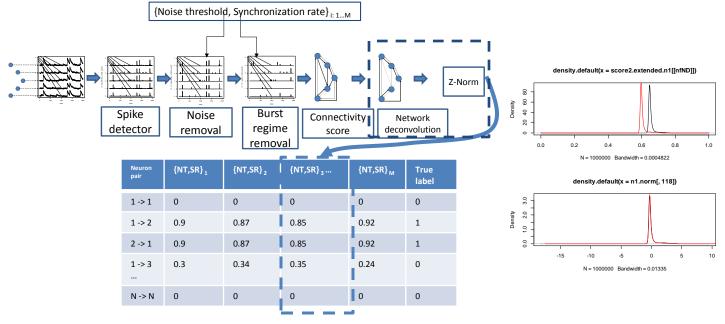
where  $\lambda_i$  being the  $i_{\mathrm{th}}$  eigenvalue of the normalized matrix

4) To compose the direct dependency matrix according to:

$$C_{dir} = UDU^{-1}$$

Where  $\emph{U}$  is the matrix of eigenvectors and  $\emph{D}$  is a diagonal matrix s.t.  $\emph{i}_{\mathsf{th}}$  diagonal element is  $\lambda_i^d$ 

Building blocks, Training and test data preparation



#### Goal:

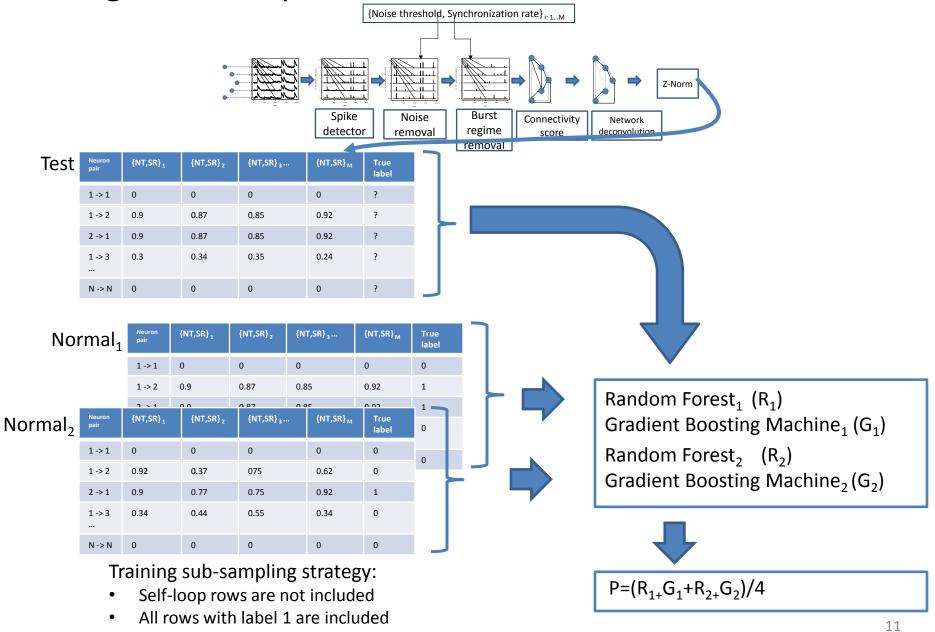
- 1. To normalize the values of the deconvolved matrix so that networks using the same parameters (i.e. NL, SR) have similar distributions.
- 2. To create data tables to train and test a supervised model

**How:** For each network we create one table s.t.:

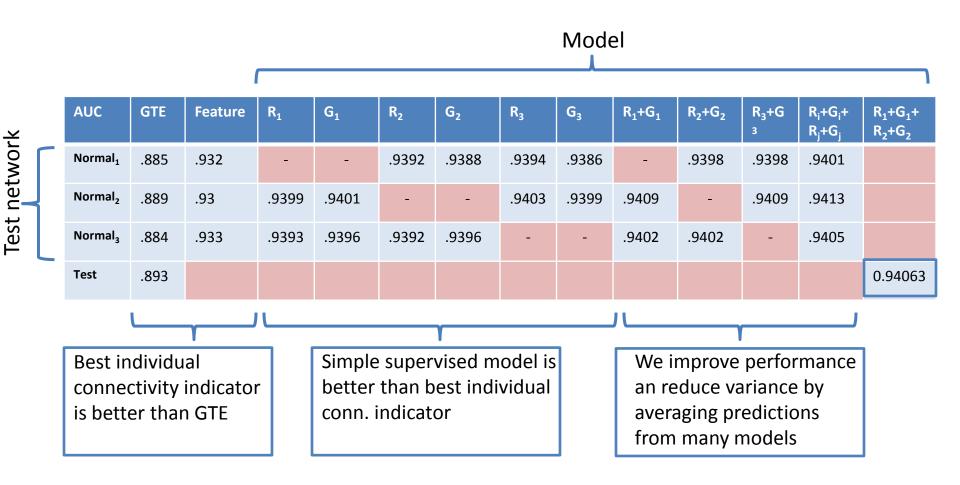
- Row: connectivity indicators for neuron pair (i,j) computed according to different Noise Levels and synchronization rates
- Column: connectivity indictors for all neuron pairs computed according to a particular Noise Level and Synchronization Rate
- Column-wise Z-normalization to normalize distributions across different networks
- Rows corresponding to self-loops, e.g. (i,i) are all 0 (We do not learn self-loops)
- We ignore directed connections, e.g. (i,j)=(j,i)

### Building blocks, Supervised model

5% of rows with label 0 are included



### Experiments



### Conclusions, limitations and future work

#### **Conclusions**

- Third best model according to the private leadeboard: AUC<sub>GTF</sub>=.893, AUC<sub>best</sub>=.94063
- To approximate a function able to combine several connectivity indicators optimized for different conditions of synchronous bursting and noise seems to be a good idea

#### Limitations

- We are unable to identify the connectivity direction and self-loops
- High computational cost due to the computation of large number of connectivity indicators (e.g. training our last model took > 48 hours on i7 laptop with 32 Gb)

#### **Future work:**

- Add few directional connectivity indicators to the predictive model (e.g. GTE)
- Increase the number of features by using a finer grid of parameters (i.e. {Noise threshold, Synchronization rate}  $_{i: 1...M}$  )
- Increase the performance of predictive models by using semi-supervised variants of random forest and gradient boosting machines